Flexibility in Contact and Symplectic Geometry

Oleg Lazarev Michael Zhao Memorial Student Colloquium

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Rolling without slipping

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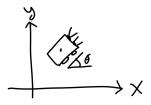
Consider a car in ℝ² with position x, y and angle θ with the x-axis; configuration space is {(x, y, θ)} = ℝ² × S¹

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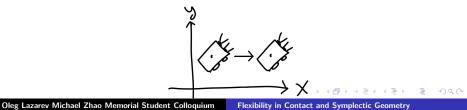
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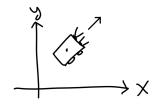
Rolling without slipping, II

 If car rolls without slipping, then θ determines direction of motion: dy/dx = tan(θ)

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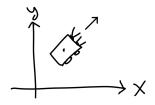


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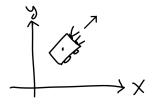


So a path (x(t), y(t), θ(t)) is non-slipping if it is tangent to hyperplane distribution ξ² := ker(dy − tan(θ)dx) ⊂ Tℝ² × S¹

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► Question: can any path in R³ be C⁰-approximated by the motion of a non-slipping car?

Formal/genuine functions

• Graph of function z(x) with its derivative: $(x, \frac{dz}{dx}, z(x)) \subset \mathbb{R}^3$

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• $(x, y(x), z(x)) \subset \mathbb{R}^3$ is graph of 'genuine' function if $\frac{dz}{dx} = y$, i.e. tangent to the hyperplane distribution $\xi^2 := \ker(dz - ydx)$

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 Example: replace ODE (df/dx)² + f(x)² df/dx = x⁵ with algebraic equation y² + yz² = x⁵; curves in this hypersurface tangent to ξ are solutions to the ODE

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- **Example:** replace ODE $(\frac{df}{dx})^2 + f(x)^2 \frac{df}{dx} = x^5$ with algebraic equation $y^2 + yz^2 = x^5$; curves in this hypersurface tangent to ξ are solutions to the ODE
- Question: can any formal function approximated by a genuine function?

Contact distribution

The contact distribution ξ and submanifolds tangent to it are the key objects.

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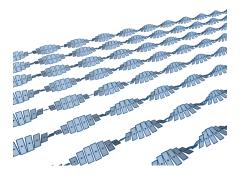


Figure: The contact distribution $\xi_{std} = \ker(dz - ydx) \subset T\mathbb{R}^3$, image due to Patrick Massot

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Contact geometry

Definition: a contact structure ξ on a manifold Y²ⁿ⁺¹ is a hyperplane distribution ξ²ⁿ = ker(α) for a 1-form α with α ∧ (dα)ⁿ ≠ 0, maximally non-integrable

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- Basic but important linear algebra fact: if Λ^k ⊂ (Y²ⁿ⁺¹, ξ) is isotropic, then k ≤ n (called Legendrian if k = n). Intuition: contact distribution is maximally non-integrable.

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Classical flexibility results

Flexibility = topological phenomenon in contact geometry

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- ► **Darboux's theorem:** any contact manifold is locally contactomorphic to $(\mathbb{R}^{2n+1}, \xi_{standard} = dz \sum_{i=1}^{n} y_i dx_i)$

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- Weinstein neighborhood theorem: any Legendrian Λⁿ ⊂ (Y²ⁿ⁺¹, ξ) has a neighborhood that is contactomorphic to neighborhood of Λ in J¹(Λ)

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Partial Differential Relations

Many geometric problems given by a PDE, e.g. existence of contact structure, contactomorphism, isotropic embedding

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Partial Differential Relations

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- Question: does h-principle hold for contact structures or isotropic submanifolds?

Rigidity in contact geometry

There are non-local, deformation stable invariants of contact manifolds, Legendrians called *contact homology* and *Legendrian contact homology*, Gromov-Witten type invariant defined using J-holomorphic curves. Related to wrapped Fukaya category, mirror symmetry...

Rigidity in contact geometry

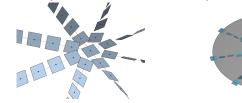
- There are non-local, deformation stable invariants of contact manifolds, Legendrians called *contact homology* and *Legendrian contact homology*, Gromov-Witten type invariant defined using J-holomorphic curves. Related to wrapped Fukaya category, mirror symmetry...
- Many Legendrian knots in (R³, ξ_{std}) are formally isotopic but not Legendrian isotopic, distinguished by Legendrian contact homology

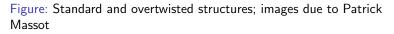


Figure: Chekanov Legendrians in \mathbb{R}^2_{xz} ; images due to John Etnyre

Rigidity in contact geometry, II

 Similarly, many contact structures are formally contactomorphic but not contactomorphic





- h-principle fails for contact manifolds, isotropic submanifolds!
 *i*_{*} is not injective on π₀; for Legendrian knots, *i*_{*} is not surjective on π₀
- Question: what is the boundary between rigidity and flexibility?

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Flexibility for isotropics

Gromov's h-principle for subcritical isotropics: two formally isotopic Λ^k₁, Λ^k₂ ⊂ (Y²ⁿ⁺¹, ξ) with k < n are genuinely isotopic

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- h-principle fails for general Legendrians (k = n) by LCH
- ▶ Definition: a Legendrian Λⁿ ⊂ Y²ⁿ⁺¹ is *loose* if n ≥ 2 and it has a 'zig-zag' in its xz-projection

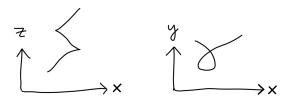


Figure: Loose chart, i.e. zig-zag, pictured in \mathbb{R}^2_{xz} and in \mathbb{R}^2_{xy}

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Loose Legendrians

Murphy's h-principle for loose Legendrians: formally isotopic loose Legendrians are Legendrian isotopic; any smooth embedding can be C⁰-approximated by a loose Legendrian.

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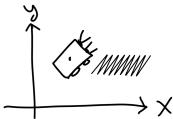


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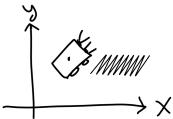


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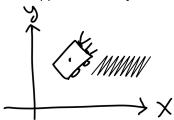
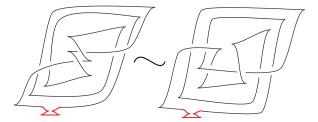


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- **Open problem:** If Λ has vanishing LCH, is it loose?

Loose Legendrians, II

Loose Chekanov knots (in high-dimensions) are Legendrian isotopic



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Symplectic manifolds

Definition a symplectic structure ω on a manifold M²ⁿ is a closed, non-degenerate 2-form ω; get [ω] ∈ H²(M; ℝ) and [ω]ⁿ ≠ 0 if M closed manifold

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Open problems: Is *i*_{*} injective on π₀ in dimension 4? Is *i*_{*} surjective on π₀ in dimensions > 4?

Weinstein domains

An exact symplectic manifold (M²ⁿ, dα) has contact boundary if (∂M, ker α) is a contact manifold

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• Weinstein: can attach a handle to an isotropic sphere $\Lambda^{k-1} \subset \partial M^{2n}$ and get a new symplectic manifold with contact boundary $M^{2n} \cup H^k_{\Lambda}$

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Weinstein domains

An exact symplectic manifold (M²ⁿ, dα) has contact boundary if (∂M, ker α) is a contact manifold

• **Example:** $(B^{2n}, \alpha_{standard} = \frac{1}{2} (\sum_{i=1}^{n} x_i dy_i - y_i dx_i))$

• Weinstein: can attach a handle to an isotropic sphere $\Lambda^{k-1} \subset \partial M^{2n}$ and get a new symplectic manifold with contact boundary $M^{2n} \cup H^k_{\Lambda}$

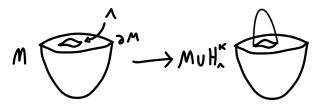


Figure: Weinstein handle attachment

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Weinstein domains, II

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• Example:
$$T^*S^n = B^{2n} \cup H^n_{\Lambda_{unknot}}$$

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Rigidity for Weinstein domains

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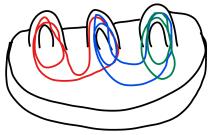


Figure: Sketch of an exotic Weinstein ball

Flexibility for Weinstein domains

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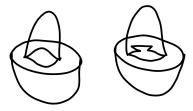


Figure: T^*S^n and $T^*S^n_{flex}$

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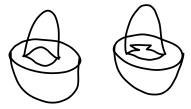


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► Cieliebak-Eliashberg: A formal Weinstein manifold W²ⁿ, n ≥ 3, has a genuine Weinstein structure. Two formally symplectomorphic flexible structures are symplectomorphic

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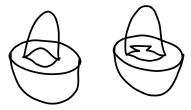


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- ► Cieliebak-Eliashberg: A formal Weinstein manifold W²ⁿ, n ≥ 3, has a genuine Weinstein structure. Two formally symplectomorphic flexible structures are symplectomorphic
- Question: can this result be used to construct symplectic structures on closed manifolds?

Oleg Lazarev Michael Zhao Memorial Student Colloquium

Modifying Weinstein presentations

 Can modify Weinstein presentation by doing handle-slides and create/cancel handles; easy to create more handles

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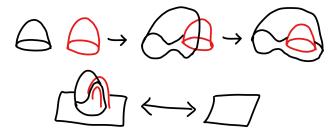


Figure: Handle-slides and handle cancellation/creation

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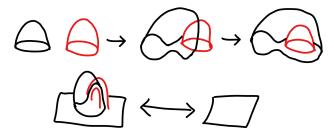


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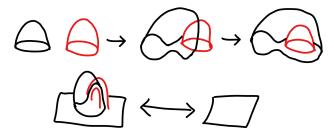


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 WCrit(M) ≥ Crit(M) ≥ rank H*(M; Z)

Modifying Weinstein presentations, II

Smale's h-cobordism theorem: if dim $M \ge 5$, $\pi_1(M) = 0$, then $Crit(M) = \text{rank } H^*(M; \mathbb{Z})$; key is Whitney trick

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Question: what is the interaction between symplectic flexibility and rigidity?