

# Extensions of the Weinstein conjecture in three dimensions

Michael Hutchings

Department of Mathematics  
University of California, Berkeley

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# Outline

- 1 Review of the Weinstein conjecture
- 2 Improvements on the Weinstein conjecture
  - More Reeb orbits
  - Short Reeb orbits
  - More general vector fields
- 3 Embedded contact homology
- 4 Some proofs

# Part 1

With apologies for boring the experts, we begin with a brief review of the Weinstein conjecture.

# Closed orbits of vector fields on three-manifolds

## Question

Let  $Y$  be a closed oriented three-manifold. Does every vector field on  $Y$  have a closed orbit?

It is easy to construct vector fields on  $T^3$  with no closed orbit (irrational rotations), but hard on  $S^3$ .

## Seifert conjecture

Every vector field on  $S^3$  has a closed orbit.

- Counterexamples: P. Schweizer ( $C^1$ ), J. Harrison ( $C^2$ ), K. Kuperberg ( $C^\infty$ ), G. Kuperberg ( $C^1$  and volume-preserving).
- The constructions involve inserting a “plug” to destroy a closed orbit without creating new ones.
- These methods yield vector fields with no closed orbit on any three-manifold.

# Hamiltonian vector fields

Consider  $\mathbb{R}^{2n}$  with the standard symplectic form

$$\omega = \sum_{i=1}^n dx_i dy_i.$$

A smooth function  $H : \mathbb{R}^{2n} \rightarrow \mathbb{R}$  determines a Hamiltonian vector field  $X_H$  by the equation  $dH = \omega(X_H, \cdot)$ . More explicitly,

$$X_H = \sum_{i=1}^n \left( \frac{\partial H}{\partial y_i} \frac{\partial}{\partial x_i} - \frac{\partial H}{\partial x_i} \frac{\partial}{\partial y_i} \right).$$

Note that  $X_H$  is tangent to each level set of  $H$ , because  $\omega(X_H, X_H) = 0$ .

## Question

Let  $Y$  be a compact regular level set of  $H : \mathbb{R}^{2n} \rightarrow \mathbb{R}$ . Must  $X_H$  have a closed orbit on  $Y$ ?

## Answer

- Yes for almost every compact regular level set (Hofer-Zehnder, Struwe).
- But no in general. There are  $C^2$  counterexamples  $H : \mathbb{R}^4 \rightarrow \mathbb{R}$  by Ginzburg-Gürel (2003), and smooth counterexamples are known in higher dimensions.

## Remark

If  $Y$  is a regular level set of  $H$ , then up to parametrization, closed orbits of  $X_H$  on  $Y$  depend only on  $Y$  and not on  $H$ . Indeed, embedded closed orbits are just leaves of the 1-dimensional **characteristic foliation** of  $Y$  defined by  $\text{Ker}(\omega|_Y)$ . These are called **closed characteristics** of  $Y$ .

# Reeb vector fields

## Definition

Let  $Y$  be a closed smooth manifold of dimension  $2n - 1$ .

A **contact form** on  $Y$  is a 1-form  $\lambda$  on  $Y$  such that  $\lambda \wedge (d\lambda)^{n-1} \neq 0$ .

A contact form  $\lambda$  determines:

- A **Reeb vector field**  $R$ , defined by  $d\lambda(R, \cdot) = 0$  and  $\lambda(R) = 1$ .
- A **contact structure**, namely the oriented  $(2n - 2)$ -plane field  $\xi = \text{Ker}(\lambda)$ .

## Definition

A **Reeb orbit** is a periodic orbit of  $R$ , i.e. a map  $\gamma : \mathbb{R}/T\mathbb{Z} \rightarrow Y$  for some  $T > 0$ , modulo reparametrization, such that  $\gamma'(t) = R(\gamma(t))$ .

# Contact dynamics and Hamiltonian mechanics

## Example

If  $Y$  is a star-shaped hypersurface in  $\mathbb{R}^{2n}$ , then

$$\lambda = \frac{1}{2} \sum_{k=1}^n (x_k dy_k - y_k dx_k)$$

restricts to a contact form on  $Y$ . The Reeb vector field is a rescaling of the Hamiltonian vector field for any Hamiltonian  $H : \mathbb{R}^{2n} \rightarrow \mathbb{R}$  having  $Y$  as a regular level set.

Here a hypersurface  $Y$  in  $\mathbb{R}^{2n}$  is called **star-shaped** if it is transverse to the radial vector field

$$\rho = \frac{1}{2} \sum_{k=1}^n \left( x_k \frac{\partial}{\partial x_k} + y_k \frac{\partial}{\partial y_k} \right).$$



# Contact dynamics and geodesic flow

Let  $M$  be a smooth manifold. The cotangent bundle  $T^*M$  has a canonical 1-form  $\lambda_{can}$  defined by

$$\lambda_{can}(q, p) = p \circ \pi_*$$

for  $q \in M$  and  $p \in T_q^*M$ , where  $\pi : T^*M \rightarrow M$  is the projection.

## Example

Choose a Riemannian metric  $g$  on  $M$ . Then the restriction of  $\lambda_{can}$  to the unit cotangent bundle

$$ST^*M = \{(q, p) \in T^*M \mid |p| = 1\}$$

is a contact form. Under the identification  $T^*M = TM$  determined by  $g$ , the Reeb vector field corresponds to the geodesic flow. Thus Reeb orbits are equivalent to (oriented) closed geodesics.

## Weinstein conjecture (1978)

Every contact form on a closed oriented odd-dimensional manifold has a Reeb orbit.

## Theorem (Taubes, 2006)

*The Weinstein conjecture is true in three dimensions: every contact form on a closed oriented three-manifold has a Reeb orbit.*

The proof uses Seiberg-Witten theory. In higher dimensions the Weinstein conjecture is open in general, although it is known in some cases.

## Part 2

We now state some theorems and conjectures generalizing the Weinstein conjecture in three dimensions. In particular:

- 1 Can one improve the lower bound on the number of Reeb orbits?
- 2 Can one prove the existence of Reeb orbits with an *a priori* upper bound on the length?
- 3 Can we replace Reeb vector fields by any more general vector fields?

(Answers: 1. Yes. 2. Maybe. 3. Yes.)

# More Reeb orbits

## Theorem (with Taubes, 2008)

*Let  $Y$  be a closed oriented three-manifold and let  $\lambda$  be a nondegenerate contact form on  $Y$ . Then:*

- *$\lambda$  has at least two embedded Reeb orbits.*
- *If  $Y$  is not  $S^3$  or a lens space, then  $\lambda$  has at least three embedded Reeb orbits.*

Here a contact form is **nondegenerate** if all Reeb orbits are nondegenerate, or “cut out transversely”, in the following sense. If  $\gamma : \mathbb{R}/T\mathbb{Z} \rightarrow Y$  is a Reeb orbit, the Reeb flow for time  $T$  induces a “linearized return map”, which is a symplectic linear map

$$P : (\xi_{\gamma(0)}, d\lambda) \rightarrow (\xi_{\gamma(0)}, d\lambda).$$

The Reeb orbit  $\gamma$  is nondegenerate if  $1 \notin \text{Spec}(P)$ . This implies that it is isolated in the free loop space.

A generic contact form is nondegenerate.

# Removing the nondegeneracy assumption

Theorem (with D. Cristofaro-Gardiner and V. Ramos, 2012)

*Every (possibly degenerate) contact form on a closed oriented three-manifold has at least two embedded Reeb orbits.*

This was new even for the standard contact structure on  $S^3$ ; an alternate proof in that case was given by Ginzburg, Hein, Hryniewicz, and Macarini. In particular, this proves the  $n = 2$  case of:

Old conjecture (Ekeland-Hofer?)

Every star-shaped hypersurface in  $\mathbb{R}^{2n}$  has at least  $n$  closed characteristics.

Various special cases have been proved by Yiming Long et al.

## The ellipsoid example

- Let  $a, b > 0$  with  $a/b$  irrational. Identify  $\mathbb{R}^4 = \mathbb{C}^2$ . Define the ellipsoid

$$E(a, b) = \left\{ z \in \mathbb{C}^2 \mid \frac{\pi|z_1|^2}{a} + \frac{\pi|z_2|^2}{b} \leq 1 \right\}.$$

Then  $Y = \partial E(a, b)$  is star-shaped, so it has a canonical contact form.

- The Reeb vector field is

$$R = 2\pi \left( \frac{1}{a} \frac{\partial}{\partial \theta_1} + \frac{1}{b} \frac{\partial}{\partial \theta_2} \right).$$

There are just two embedded Reeb orbits: the circles where  $z_1 = 0$  or  $z_2 = 0$ .

- One can take the quotient by the action of a finite cyclic group to obtain a contact form on a lens space with only two embedded Reeb orbits.

# Infinitely many Reeb orbits?

- Embarrassingly, the above are the only known examples of contact forms on closed three-manifolds with only finitely many embedded Reeb orbits.
- Hofer-Wysocki-Zehnder, 2003: A generic closed star-shaped hypersurface in  $\mathbb{R}^4$  has infinitely many embedded Reeb orbits.
- Colin-Honda, 2008: For many contact structures  $\xi$  on closed oriented three-manifolds  $Y$ , every contact form  $\lambda$  with  $\text{Ker}(\lambda) = \xi$  has infinitely many embedded Reeb orbits. (Proof uses linearized contact homology.)

## Conjecture

If  $Y$  is a closed oriented connected three-manifold which is not  $S^3$  or a lens space, then every contact form on  $Y$  has infinitely many embedded Reeb orbits.

## Short Reeb orbits

The **length** or **symplectic action** of a Reeb orbit  $\gamma$  is defined by

$$\mathcal{A}(\gamma) = \int_{\gamma} \lambda > 0.$$

### Question

Given a closed contact three-manifold  $(Y, \lambda)$ , does there exist a Reeb orbit with an *a priori* upper bound on the length?

### Answer

Not without information, because one can multiply the contact form by a positive constant  $r$ , and this multiplies the lengths of all Reeb orbits by  $r$ .

But we can obtain a statement which is invariant under scaling as follows.



Define the **volume** of a contact 3-manifold  $(Y, \lambda)$  by

$$\text{vol}(Y, \lambda) = \int_Y \lambda \wedge d\lambda.$$

### Question

Given a closed contact 3-manifold  $(Y, \xi)$ , does there exist  $c(Y, \xi) \in \mathbb{R}$  such that every contact form  $\lambda$  with  $\text{Ker}(\lambda) = \xi$  has a Reeb orbit  $\gamma$  with

$$\mathcal{A}(\gamma)^2 \leq c(Y, \xi) \text{vol}(Y, \lambda)$$

### Short Reeb orbit conjecture

For any closed contact 3-manifold  $(Y, \lambda)$ , there exists a Reeb orbit  $\gamma$  with

$$\mathcal{A}(\gamma)^2 \leq \text{vol}(Y, \lambda).$$

We can (with Cristofaro-Gardiner and Ramos) prove a much weaker, “asymptotic” version of this which we will state later.

## Example 1: a prequantization form times an $S^1$ -invariant function

- Let  $\Sigma$  be a Riemann surface and let  $\rho : Y \rightarrow \Sigma$  be a principal  $S^1$ -bundle with Euler class  $e > 0$ . Let  $\omega$  be a symplectic form on  $\Sigma$  with area  $2\pi e$ . Let  $A$  be a connection 1-form on  $Y$  with curvature  $\omega$ . Let  $f : \Sigma \rightarrow \mathbb{R}$  be a positive function. Let  $\lambda = (\rho^* f)A$ . Then  $\lambda$  is a contact form on  $Y$ .
- If  $x \in \Sigma$  is a critical point of  $f$ , then  $\rho^{-1}(x) \subset Y$  is a Reeb orbit with action  $\mathcal{A}(\rho^{-1}(x)) = 2\pi f(x)$ . (There may also be other Reeb orbits.)
- The volume is given by

$$\text{vol}(Y, \lambda) = 2\pi \int_{\Sigma} f^2 \omega \geq 4\pi^2 e \min(f).$$

- So the conjecture holds in this case, with equality if and only if  $e = 1$  and  $f$  is constant.

## Example 2: systolic inequalities

- Let  $g$  be a Riemannian metric on  $S^2$  with area  $4\pi$ . Let  $\lambda$  be the canonical contact form on  $STS^2$  whose Reeb vector field is the geodesic flow. The symplectic action of a Reeb orbit agrees with the length of the corresponding geodesic.
- Let  $Y$  be the universal (double) cover of  $STS^2$  and let  $\tilde{\lambda}$  be the pullback of the contact form. This has volume  $16\pi^2$ . Reeb orbits are “even” geodesics (geodesics which determine plane curves with odd rotation number). So the conjecture says that there is an even geodesic of length  $\leq 4\pi$ .
- This is sharp for the round metric. (A great circle is an odd geodesic, but its double cover is even.)
- The Calabi-Croke example of two flat equilateral triangles glued together gives a metric on  $S^2$  with area  $4\pi$  and no closed geodesic of length  $\leq 2\pi$ . However it still has an even geodesic of length  $< 4\pi$ . (Exercise.)

# More general vector fields

Let  $Y$  be a closed oriented 3-manifold.

## Definition

- A **stable Hamiltonian structure** on  $Y$  is a pair  $(\lambda, \omega)$  where  $\lambda$  is a 1-form,  $\omega$  is a closed 2-form,  $\lambda \wedge \omega > 0$ , and  $d\lambda = f\omega$  where  $f : Y \rightarrow \mathbb{R}$  is a smooth function.
- The associated “Reeb vector field”  $R$  is defined by  $\omega(R, \cdot) = 0$  and  $\lambda(R) = 1$ .

## Example

If  $\lambda$  is a contact form, then  $(\lambda, d\lambda)$  is a stable Hamiltonian structure with  $f \equiv 1$ , and  $R$  agrees with the usual Reeb vector field.

## Example

If  $\phi$  is a symplectomorphism of a closed oriented symplectic 2-manifold  $(\Sigma, \omega_\Sigma)$ , then the mapping torus  $\Sigma \rightarrow Y_\phi \rightarrow S^1$  has a stable Hamiltonian structure with  $\omega$  determined by  $\omega_\Sigma$ , and  $\lambda$  pulled back from the canonical 1-form on  $S^1$ . Here  $f \equiv 0$ . Periodic orbits of the vector field  $R$  correspond to periodic orbits of the map  $\phi$ .

In particular, if  $\Sigma = T^2$  and  $\phi$  is an irrational rotation, then  $R$  has no periodic orbits. But this is a rare exception:

## Theorem (with Taubes, 2008)

*If  $Y$  is a closed oriented connected three-manifold which is not a  $T^2$ -bundle over  $S^1$ , then for every stable Hamiltonian structure on  $Y$ , the associated “Reeb vector field”  $R$  has a periodic orbit.*

More general vector fields???

## Part 3

We now review embedded contact homology (ECH), which is the main tool which we use to prove our theorems. This inputs a contact three-manifold  $(Y, \lambda)$  and outputs a homology which keeps track of the Reeb orbits and certain holomorphic curves between them.

# Embedded contact homology

Embedded contact homology depends on:

- A closed 3-manifold  $Y$ .
- A nondegenerate contact form  $\lambda$  on  $Y$ .
- A homology class  $\Gamma \in H_1(Y)$ .

$ECH(Y, \lambda, \Gamma)$  is the homology of a chain complex over  $\mathbb{Z}/2$ . (One can also use  $\mathbb{Z}$  coefficients).

A chain complex generator is a finite set of pairs  $\alpha = \{(\alpha_i, m_i)\}$  where:

- The  $\alpha_i$ 's are distinct embedded Reeb orbits.
- The  $m_i$ 's are positive integers.
- $\sum_i m_i [\alpha_i] = \Gamma \in H_1(Y)$ .
- $m_i = 1$  when  $\alpha_i$  is hyperbolic (i.e. the linearized return map has real eigenvalues).

# The differential

Choose a generic almost complex structure  $J$  on  $\mathbb{R} \times Y$  such that:

- $J(\partial_s) = R$ , where  $s$  denotes the  $\mathbb{R}$  coordinate.
- $J(\xi) = \xi$  and  $d\lambda(v, Jv) \geq 0$  for  $v \in \xi$ .
- $J$  is  $\mathbb{R}$ -invariant.

If  $\alpha$  and  $\beta$  are two chain complex generators, the differential coefficient  $\langle \partial\alpha, \beta \rangle \in \mathbb{Z}/2$  counts  $J$ -holomorphic curves  $C$  in  $\mathbb{R} \times Y$ , modulo the  $\mathbb{R}$  action, which are asymptotic (as currents) to  $\alpha$  as  $s \rightarrow +\infty$  and to  $\beta$  as  $s \rightarrow -\infty$ , and which have “ECH index”  $I(C) = 1$ .

The precise definition of the ECH index  $I$  is a bit complicated. It turns out that the condition  $I(C) = 1$  forces  $C$  to be embedded (except possibly for multiple covers of  $\mathbb{R}$ -invariant cylinders), hence the name “embedded contact homology”.

## Theorem (with Taubes, 2007)

$$\partial^2 = 0.$$



# The $U$ map

- There is also a degree 2 map

$$U : ECH_*(Y, \lambda, \Gamma) \rightarrow ECH_{*-2}(Y, \lambda, \Gamma).$$

This is induced by a chain map which counts  $J$ -holomorphic curves with ECH index 2 that pass through a base point in  $\mathbb{R} \times Y$ . The  $U$  map is well-defined when  $Y$  is connected.

- The  $U$  map is very important in applications, because it is known to be nontrivial, and thus leads to the existence of many holomorphic curves with geometric consequences.

# Isomorphism with Seiberg-Witten Floer cohomology

## Theorem (Taubes, 2008)

*If  $Y$  is connected, then there is a canonical isomorphism of relatively graded modules*

$$ECH_*(Y, \lambda, \Gamma) \simeq \widehat{HM}^{-*}(Y, \mathfrak{s}_\xi + \Gamma).$$

*Here  $\widehat{HM}^*$  denotes Seiberg-Witten Floer cohomology as defined by Kronheimer-Mrowka, and  $\mathfrak{s}_\xi + \Gamma$  is a spin-c structure determined by  $\xi$  and  $\Gamma$ . This isomorphism identifies the  $U$  map on  $ECH$  with an analogous map on  $\widehat{HM}^*$ .*

In particular,  $ECH$  is a topological invariant of  $Y$ ,  $\xi$  and  $\Gamma$ .

In fact, both sides have absolute gradings by homotopy classes of oriented plane fields, and the isomorphism respects these absolute gradings (Cristofaro-Gardiner, 2012), so one can write the isomorphism as  $ECH_p(Y, \lambda) \simeq \widehat{HM}^p(Y)$  where  $p$  is a homotopy class of oriented plane fields.

# Some consequences of the isomorphism

Using properties of  $\widehat{HM}$  due to Kronheimer-Mrowka, we deduce the following:

- $ECH_*(Y, \lambda, \Gamma)$  is finitely generated in each grading  $*$ .

If  $c_1(\xi) + 2 \text{PD}(\Gamma)$  is torsion (such  $\Gamma$  always exist), then  $ECH_*(Y, \lambda, \Gamma)$  has a noncanonical  $\mathbb{Z}$ -grading, and:

- $ECH_*(Y, \lambda, \Gamma)$  vanishes when the grading  $*$  is sufficiently small
- $ECH_*(Y, \lambda, \Gamma)$  is nonzero in infinitely many gradings
- If the grading  $*$  is sufficiently large then

$$U : ECH_*(Y, \lambda, \Gamma) \rightarrow ECH_{*-2}(Y, \lambda, \Gamma).$$

# Deducing the Weinstein conjecture

## Corollary

*If  $\lambda$  is nondegenerate, and if  $c_1(\xi) + 2 \text{PD}(\Gamma)$  is torsion, then there exists a nonempty ECH generator  $\alpha = \{(\alpha_i, m_i)\}$  with  $\sum_i m_i [\alpha_i] = \Gamma$ .*

*Proof.* We know that  $ECH_*(Y, \xi, \Gamma)$  is infinitely generated. If there is no nonempty ECH generator in the class  $\Gamma$ , then

$$ECH_*(Y, \xi, \Gamma) = \begin{cases} \mathbb{Z}/2, & \Gamma = 0, \\ 0, & \Gamma \neq 0. \end{cases}$$

which is a contradiction. (Here the  $\mathbb{Z}/2$  is generated by the empty set of Reeb orbits.) □

# Filtered ECH

If  $\alpha = \{(\alpha_i, m_i)\}$  is an ECH generator, define its **symplectic action** by

$$\mathcal{A}(\alpha) = \sum_i m_i \int_{\alpha_i} \lambda.$$

It follows from the conditions on  $J$  that the differential decreases symplectic action: if  $\langle \partial\alpha, \beta \rangle \neq 0$  then  $\mathcal{A}(\alpha) > \mathcal{A}(\beta)$ . Thus we can make:

## Definition

Given  $L \in \mathbb{R}$ , we can define  $ECH^L(Y, \lambda, \Gamma)$ , called **filtered ECH**, to be the homology of the subcomplex generated by  $\alpha$  with  $\mathcal{A}(\alpha) < L$ .

Unlike the usual ECH, filtered ECH depends heavily on the contact form  $\lambda$ .

# The ECH spectrum

## Definition

If  $0 \neq \sigma \in ECH(Y, \xi, \Gamma)$ , define  $c_\sigma(Y, \lambda)$  to be the infimum of  $L$  such that  $\sigma$  is in the image of the map  $ECH^L(Y, \lambda, \Gamma) \rightarrow ECH(Y, \xi, \Gamma)$ .

The numbers  $c_\sigma(Y, \lambda)$  are the “ECH spectrum” of  $(Y, \lambda)$ .

## Remark

By definition, there exists an ECH generator with symplectic action equal to  $c_\sigma(Y, \lambda)$ . So if  $\sigma \neq [\emptyset]$ , then there exists a Reeb orbit of action less than or equal to  $c_\sigma(Y, \lambda)$ .

One can also define  $c_\sigma(Y, \lambda)$  when  $\lambda$  is degenerate by taking a limit of nondegenerate contact forms.

## Example: the boundary of an ellipsoid

- Suppose  $Y = \partial E(a, b)$  with its canonical contact form  $\lambda$ .
- If  $a/b$  is irrational then  $\lambda$  is nondegenerate: the linearized return map around  $\gamma_1$ , respectively  $\gamma_2$ , is rotation by  $2\pi a/b$ , respectively  $2\pi b/a$ .
- The chain complex generators have the form  $\gamma_1^a \gamma_2^b$  with  $a, b \in \mathbb{N}$ . The symplectic action of such a generator is  $am + bn$ .
- The differential vanishes because every generator has even grading.
- So in this case the numbers in the ECH spectrum are the nonnegative linear combinations of  $a$  and  $b$ .
- If we write the generators in order of increasing symplectic action as  $\zeta_0, \zeta_1, \zeta_2, \dots$  then  $U\zeta_k = \zeta_{k-1}$  for  $k > 0$  and  $U\zeta_0 = 0$ .

## Part 4

We now outline how embedded contact homology can be used to prove the existence of two Reeb orbits (and a bit more) for any contact form on a closed three-manifold.



# Asymptotics of the ECH spectrum

The key result is the following:

**Theorem (with D. Cristofaro-Gardiner and V. Ramos, 2012)**

*Let  $(Y, \lambda)$  be a closed connected contact three-manifold, possibly degenerate. Let  $\{\sigma_k\}_{k \geq 1}$  be a sequence in  $ECH(Y, \xi, \Gamma)$  with  $U\sigma_{k+1} = \sigma_k$ . (Such a sequence always exists by the isomorphism with  $\widehat{HM}$ .) Then*

$$\lim_{k \rightarrow \infty} \frac{c_{\sigma_k}(Y, \lambda)^2}{k} = 2 \operatorname{vol}(Y, \lambda).$$

Recall that  $c_{\sigma_k}(Y, \lambda)$  is the length of a finite set of (possibly multiply covered) Reeb orbits. So this theorem relates the volume of  $(Y, \lambda)$  to the lengths of certain distinguished sets of Reeb orbits.

## Example: the boundary of an ellipsoid

Let us check this theorem when  $Y = \partial E(a, b)$ , and  $\sigma_k = \zeta_k$ .

- $c_{\zeta_k}(\partial E(a, b)) = L$  where the triangle bounded by the  $x$  axis, the  $y$  axis, and the line  $ax + by = L$  encloses  $k + 1$  lattice points.
- This triangle has area  $L^2/2ab$ , so

$$k = \frac{L^2}{2ab} + O(L).$$

- Thus

$$\lim_{k \rightarrow \infty} \frac{c_{\zeta_k}(\partial E(a, b))^2}{k} = 2ab.$$

- It is an exercise to check that

$$\text{vol}(\partial E(a, b)) = ab.$$

# A key lemma

## Lemma

*Let  $(Y, \lambda)$  be a closed connected contact three-manifold. Suppose there are only finitely many embedded Reeb orbits  $\gamma_1, \dots, \gamma_k$ . Then:*

- *For any  $\sigma \in ECH_*(Y, \xi, \Gamma)$ , the number  $c_\sigma(Y, \lambda)$  is a nonnegative integer linear combination of  $\mathcal{A}(\gamma_1), \dots, \mathcal{A}(\gamma_k)$ .*
- *If  $U\sigma \neq 0$ , then  $c_{U\sigma}(Y, \lambda) < c_\sigma(Y, \lambda)$ .*

If  $\lambda$  is nondegenerate this follows directly from the definitions. The proof when  $\lambda$  is degenerate requires a limiting and Gromov compactness argument.

## Remark

If there are infinitely many embedded Reeb orbits, then it is possible that  $c_{U\sigma}(Y, \lambda) = c_\sigma(Y, \lambda)$ . For example this happens sometimes when  $Y = \partial E(a, b)$  and  $a/b$  is rational.

# Proof of the existence of two embedded Reeb orbits

- Let  $(Y, \lambda)$  be a closed connected contact three-manifold. Suppose there is only one embedded Reeb orbit  $\gamma$ , with action  $T$ .
- Choose  $\Gamma \in H_1(Y)$  such that  $c_1(\xi) + 2\text{PD}(\Gamma)$  is torsion, and let  $\{\sigma_k\}_{k \geq 1}$  be a sequence of nonzero classes in  $ECH(Y, \lambda, \Gamma)$  with  $U\sigma_{k+1} = \sigma_k$ .
- By the Key Lemma,  $c_{\sigma_k}(Y, \lambda) = m_k T$  where  $m_k$  is a nonnegative integer and  $m_k < m_{k+1}$ .
- Therefore

$$\lim_{k \rightarrow \infty} \frac{c_{\sigma_k}(Y, \lambda)}{k} \geq T.$$

- This contradicts the theorem on the asymptotics of the ECH spectrum which asserts that

$$\lim_{k \rightarrow \infty} \frac{c_{\sigma_k}(Y, \lambda)^2}{k} = 2 \text{vol}(Y, \lambda) < \infty.$$

# Relation to the short Reeb orbit conjecture

## Theorem (same collaborators)

*Let  $(Y, \lambda)$  be a closed connected contact three-manifold. Then at least one of the following is true:*

- *There exists a Reeb orbit  $\gamma$  with  $\mathcal{A}(\gamma)^2 \leq \text{vol}(Y, \lambda)$ .*
- *There exist at least three embedded Reeb orbits.*

To prove this, we will show that if there are only two embedded Reeb orbits  $\gamma_1$  and  $\gamma_2$ , with actions  $T_1$  and  $T_2$ , then

$$T_1 T_2 \leq \text{vol}(Y, \lambda).$$

To do so, let  $\{\sigma_k\}_{k \geq 1}$  be as before. Then  $c_{\sigma_k}(Y, \lambda) = m_k T_1 + n_k T_2$  with  $m_k, n_k \in \mathbb{N}$  and  $m_k T_1 + n_k T_2 < m_{k+1} T_1 + n_{k+1} T_2$ . As in the ellipsoid example, it follows that

$$\lim_{k \rightarrow \infty} \frac{c_{\sigma_k}(Y, \lambda)^2}{k} \geq 2T_1 T_2.$$